

DCW Submersible DC to DC LVDT Displacement Transducer

- High accuracy
- High resolution
- Voltage / 4-20mA output
- High cycle life
- Submersible
- Stainless steel



DISPLACEMENT

These transducers are for displacement / position measurement. They make an accurate position measurement of the movement of the armature (the sliding part) relative to the body of the displacement transducer.

This transducer uses the Linear Variable Differential Transformer (LVDT) principle which means that it is probably the most robust and reliable position sensor type available. The strength of the LVDT sensor's principle is that there is no electrical contact across the transducer position sensing element which for the user of the sensor means clean data, infinite resolution and a very long life.

Our DC to DC LVDT transducer has all of the benefits of the LVDT sensor principle with the added convenience of built-in LVDT electronics enabling a dc supply and dc output. As an option we can offer a 4-20mA 2 wire connection to the transducer on some models.

Our submersible displacement transducers are designed to make measurements whilst submerged in suitable liquids. Fluids which are non-magnetic can be allowed to flood the armature tube without affecting the operation of the transducer.

This series of displacement transducer is available as either an unguided, captive or spring return version.

Unguided version.

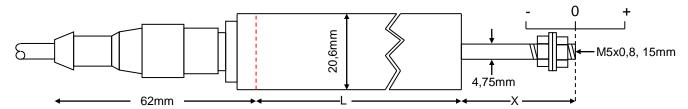
Shown with standard cable assembly, see below for options

On our unguided LVDTs the armature assembly is a separate component, to make a measurement the user must guide the armature inside the body without touching the sides. Unguided position measurement transducers are appropriate where external guidance is available and give truly non-contact operation

n 5.97mm 20,6mm 6,80mm Ъ M5x0,8, 15mm 4.75mm 62mm .X Linearity error Armature Inward over-L Х Total weight Туре Range (% F.S.) weight travel 125g 1,4g **DCW100** 68mm ±2.5mm <±0,5/±0,25 33mm 10mm DCW200 $<\pm 0.5/\pm 0.25$ 68mm 33mm 125g 1,8g 7mm ±5mm 125g DCW300 ±7,5mm <±0,5/±0,25 68mm 33mm 1,8g 5mm DCW400 <±0,5/±0,25 68mm 33mm 125g 1,9g ±10mm 2mm **DCW500** ±12,5mm <±0,5/±0,25/±0,1 203mm 38mm 243g 19g 10mm DCW1000 <±0,5/±0,25/±0,1 231mm 63mm 300g 26g ±25mm 23mm DCW2000 <±0,5/±0,25/±0,1 354mm 76mm 399g 40g 10mm ±50mm 57g ±75mm DCW3000 <±0,5/±0,25/±0,1 470mm 114mm 527g 23mm 71g DCW4000 ±100mm $<\pm0,5/\pm0,25/\pm0,1$ 503mm 127mm 655g 10mm <±0,5/±0,25 DCW6000 ±150mm 707mm 178mm 882g 104q 10mm DCW8000 254mm 142g ±200mm $<\pm 0,5/\pm 0,25$ 909mm 1,3kg 36mm www.rdpe.com/za/dcw.pdf 20150925 1/5

Captive guided version.

Our captive guided displacement transducer has bearings to guide the armature inside the measurement sensor. Captive LVDTs are for position measurement applications where guidance may be poor and end bearings may be required.



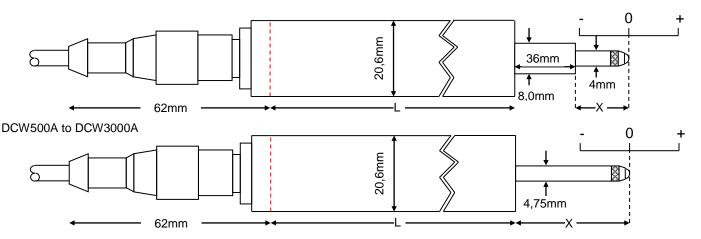
Shown with standard cable assembly, see below for options

Туре	Range	Range Linearity error (% L X		Х	Total weight	Inward over-	Outward over-
	40.5	F.S.)	000		070	travel	travel
DCW500B	±12,5mm	<±0,5/±0,25/±0,1	203mm	38mm	370g	10mm	28mm
DCW1000B	±25mm	<±0,5/±0,25/±0,1	231mm	63mm	428g	17mm	25mm
DCW2000B	±50mm	<±0,5/±0,25/±0,1	354mm	76mm	541g	10mm	28mm
DCW3000B	±75mm	<±0,5/±0,25/±0,1	470mm	114mm	655g	23mm	28mm
DCW4000B	±100mm	<±0,5/±0,25/±0,1	503mm	127mm	797g	10mm	28mm
DCW6000B	±150mm	<±0,5/±0,25	707mm	178mm	1,1kg	10mm	35mm
DCW8000B	±200mm	<±0,5/±0,25	909mm	254mm	1,5kg	36mm	41mm
DCW10000B	±250mm	<±0,5/±0,25	1094mm	305mm	1,7kg	36mm	47mm
DCW15000B	±375mm	<±0,5	1493mm	406mm	2,2kg	10mm	28mm
DCW18500B	±470mm	<±0,5	1766mm	508mm	2,6kg	23mm	35mm

Spring return version.

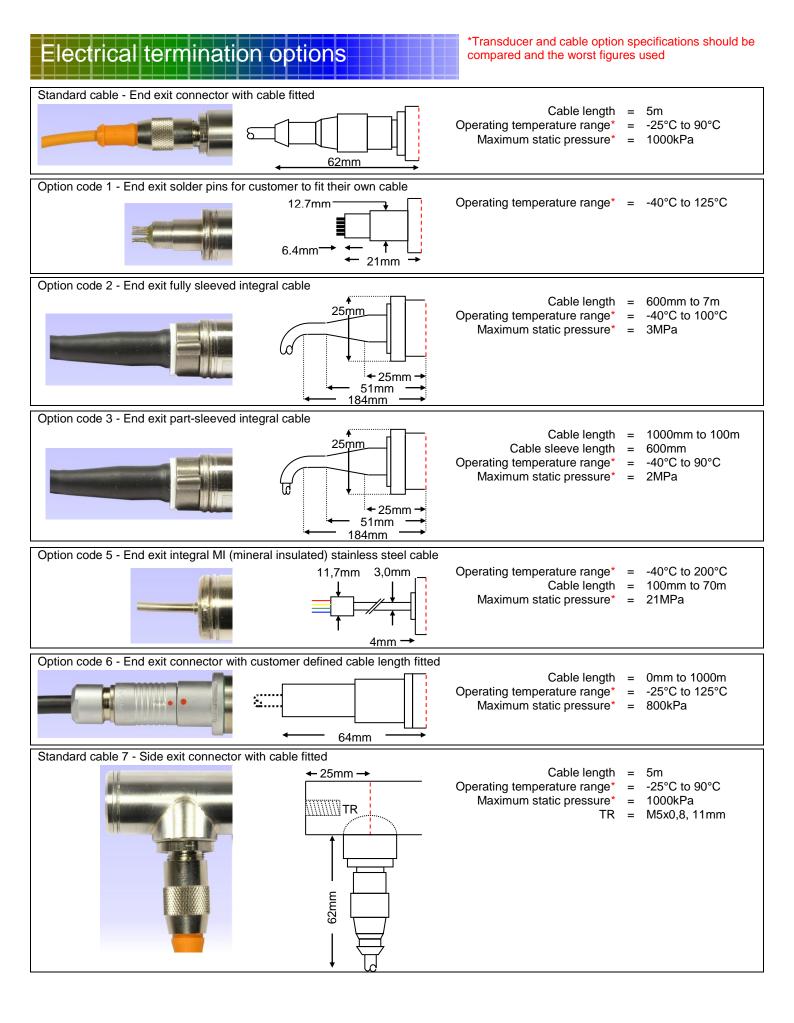
Our spring displacement transducer has bearings to guide the armature inside the measurement sensor and a spring which pushes the armature to the fully out position. Spring return LVDTs are appropriate where it is not possible to connect the transducer armature to the moving component being measured.

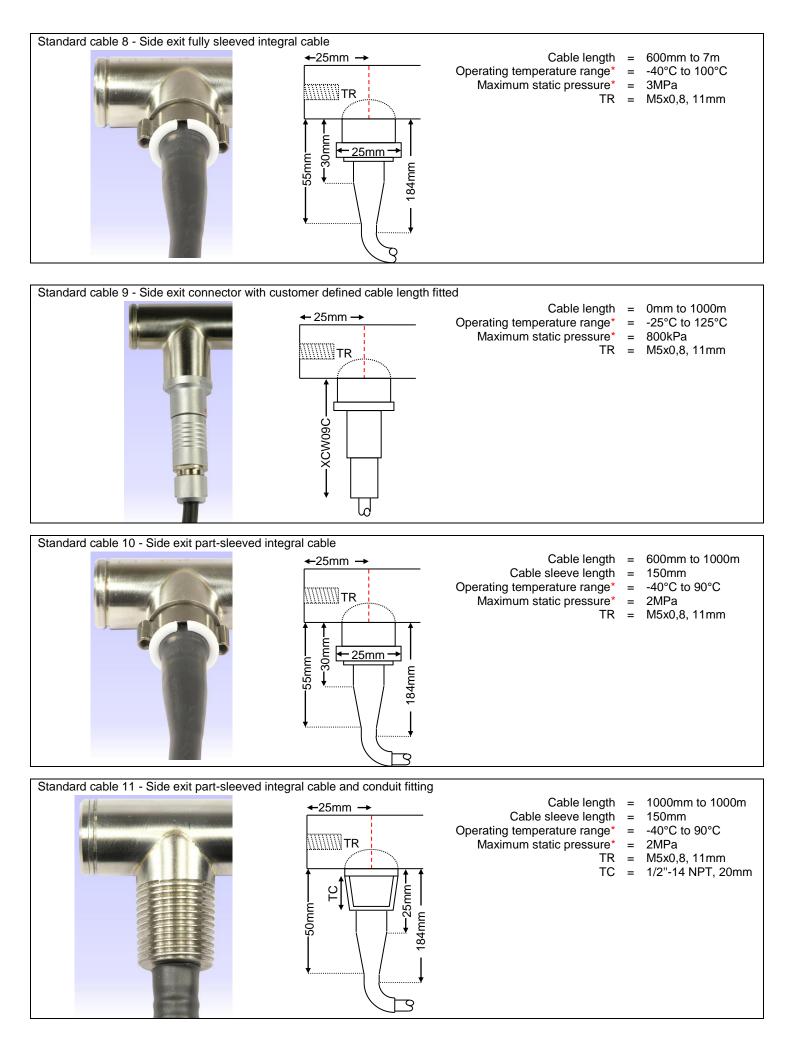
DCW100A to DCW400A



Shown with standard cable assembly, see below for options

Туре	Range	Linearity error (%	L	Х	Total	Spring force	Spring	Inward over-	Outward over-
		F.S.)			weight	at X	rate	travel	travel
DCW100A	±2,5mm	<±0,5/±0,25	68mm	11mm	135g	0,9N	0,9N/cm	2mm	1mm
DCW200A	±5mm	<±0,5/±0,25	68mm	13mm	136g	0,9N	0,8N/cm	0mm	1mm
DCW300A	±7,5mm	<±0,5/±0,25	68mm	18mm	137g	1,3N	0,6N/cm	2mm	1mm
DCW400A	±10mm	<±0,5/±0,25	68mm	22mm	138g	1,7N	0,8N/cm	2mm	1mm
DCW500A	±12,5mm	<±0,5/±0,25/±0,1	203mm	38mm	257g	1,2N	0,2N/cm	6mm	28mm
DCW1000A	±25mm	<±0,5/±0,25/±0,1	231mm	63mm	314g	1,9N	0,3N/cm	4mm	25mm
DCW2000A	±50mm	<±0,5/±0,25/±0,1	354mm	76mm	428g	4,1N	0,4N/cm	6mm	28mm
DCW3000A	±75mm	<±0,5/±0,25/±0,1	470mm	114mm	541g	5,4N	0,4N/cm	15mm	28mm





Specification		
	Supply voltage (dual)	±12V to ±20V dc, 30mA (typical)
	Supply voltage (single, must be floating)	24V to 40V dc, 30mA (typical)
	Change in output for change in supply	5mV/V
V output	Output load	10kOhms
v ouipui	Output ripple	30mV (peak-to-peak typical)
	Electrical output bandwidth	200Hz
	Output impedance	2 Ohms
	Operating temperature range	-50°C to 80°C
	Supply voltage	12V to 36V dc
	Max loop resistance	(Supply voltage-11) x 50 Ohms
4-20mA output (>=±12,5mm)	Output ripple	50uA (peak-to-peak)
	Electrical output bandwidth	200Hz
	Operating temperature range	-10°C to 70°C
	Temperature coefficient (zero)	±0,01% F.S. /°C (typical)
Both outputs	Temperature coefficient (span)	±0,03% F.S. /°C (typical)
	Maximum static pressure	21MPa

Output details							
Option code	Note	- position	0	+ position			
Standard		-5V (+0% - 5%)	0V	+5V (+0% - 5%)			
TM0627		+5V (+0% - 5%)	0V	-5V (+0% - 5%)			
TM85A		0V	5V	10V (+0% - 5%)			
TM85B		10V (+0% - 5%)	5V	0V			
TM0321A	>=±12,5mm	4mA	12mA	20mA			
TM0321B	>=±12,5mm	20mA	12mA	4mA			

All dimensions and specifications are nominal.

Due to our policy of on-going development, specifications may change without notice. Any modification may affect some or all of the specifications for our equipment.

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